



# ارتعاشات غیر خطی

## Perturbation theory, Duffing Equation

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Duffing eq:  $\ddot{u} + u + \epsilon u^3 = 0$ ,  $\epsilon \ll 1$ , cubic nonlinearity

straight forward expansion,  $u = u_0 + \epsilon u_1 + O(\epsilon^2)$

$\epsilon^0$ :  $\ddot{u}_0 + u_0 = 0 \rightarrow u_0 = a \cos(t + \beta)$  I

$\epsilon^1$ :  $\ddot{u}_1 + u_1 = -u_0^3 \rightarrow \ddot{u}_1 + u_1 = -a^3 \cos^3(t + \beta)$

$\cos^3 \theta = \frac{1}{4} \cos 3\theta + \frac{3}{4} \cos \theta$

$\Rightarrow \ddot{u}_1 + u_1 = -\frac{a^3}{4} \cos 3\theta - \frac{3a^3}{4} \cos \theta$



$$\ddot{u}_1 + u_1 = \underbrace{-\frac{a^3}{4} \cos 3\theta}_{(1)} - \underbrace{\frac{3a^3}{4} \cos \theta}_{(2)}, \quad \theta = t + \beta$$

①  $u_1 = A \cos 3\theta + B \sin 3\theta \rightarrow \dot{u}_1 = -3A \sin(3t + 3\beta) + 3B \cos(3t + 3\beta)$

$\rightarrow \ddot{u}_1 = -9A \cos(3t + 3\beta) - 9B \sin(3t + 3\beta)$

$-9A \cos(3t + 3\beta) - 9B \sin(3t + 3\beta) = -\frac{a^3}{4} \cos(3t + 3\beta)$

$\Rightarrow B = 0, \quad -9A = -\frac{a^3}{4} \Rightarrow A = \frac{a^3}{36}$

②  $u_1 = At \sin(t + \beta) \rightarrow \dot{u}_1 = \sqrt{\quad}, \quad \ddot{u}_1 = \sqrt{\quad} \Rightarrow A = \frac{-3a^3}{8}$

جواب خصوصی  $u_1 = \frac{1}{32} a^3 \cos(3t + 3\beta) - \frac{3}{8} t a^3 \sin(t + \beta)$  ②  $\Rightarrow$  
 $u = u_0 + \epsilon u_1$ 
 SFCE  
 (I) (II)



حل معادله دافنیک با روش Multiple scale

$$\ddot{u} + u + \epsilon u^3 = 0, \quad u(t, \epsilon) = u_0(T_0, T_1) + \epsilon u_1(T_0, T_1) + \dots$$

$$\epsilon^0: D_0^2 u_0 + u_0 = 0 \Rightarrow u_0 = a(T_1) \cos(T_0 + \beta(T_1))$$

$$\epsilon^1: D_0^2 u_1 + u_1 = -2D_1 D_0 u_0 - u_0^3, \quad a' = \frac{\partial a(T_1)}{\partial T_1}$$

$$-2D_1(D_0 u_0) = -2D_1(-a(T_1) \sin(T_0 + \beta(T_1))), \quad = 2a' \sin(T_0 + \beta) + 2a\beta' \cos(T_0 + \beta)$$

$$-u_0^3 = -a^3 \cos^3(T_0 + \beta) = -\frac{a^3}{4} \cos(3T_0 + 3\beta) - \frac{3}{4} a^3 \cos(T_0 + \beta)$$



$$D_0^2 u_1 + u_1 = \underbrace{2a' \sin(T_0 + \beta)} + \underbrace{2a\beta' \cos(T_0 + \beta)} + \underbrace{-\frac{a^3}{4} \cos(3T_0 + 3\beta) - \frac{3}{4}a^3 \cos(T_0 + \beta)}$$

Eliminating secular term:  $a' = 0 \Rightarrow a = a_0 =$  ثابت

$$\Rightarrow \underbrace{2a\beta' - \frac{3a^3}{4}} = 0 \quad a \neq 0 \Rightarrow \beta' = \frac{3a_0^2}{8} \Rightarrow \beta = \frac{3a_0^2}{8} T_1 + \beta_0$$

$$D_0^2 u_1 + u_1 = -\frac{a^3}{4} \cos(3T_0 + 3\beta) \Rightarrow u_1 = A \cos(3T_0 + 3\beta)$$

$$u_1 = \frac{a^3}{32} \cos(3T_0 + 3\beta)$$

$$\Rightarrow u = u_0 + \epsilon u_1 = a \cos(T_0 + \beta) + \frac{\epsilon a^3}{32} \cos(3T_0 + 3\beta)$$



$$\Rightarrow u = a_0 \cos\left(T_0 + \frac{3a_0^2 T_1}{8} + \beta_0\right) + \frac{\epsilon a_0^3}{32} \cos\left(3T_0 + \frac{9a_0^2 T_1}{8} + 3\beta_0\right) + o(\epsilon^2)$$

$$\Rightarrow u = a_0 \cos\left(t + \frac{3a_0 \epsilon t}{8} + \beta_0\right) + \frac{\epsilon a_0^3}{32} \cos\left(3t + \frac{9a_0 \epsilon t}{8} + 3\beta_0\right)$$

MS

تقریب حل معادله دامینیک با روش

MATLAB جزئیات روش را اینجا کنید

SFE - 1

MS - 2

ode45 ← Numerical - 3

$$u(0) = 1, \quad \dot{u}(0) = 0, \quad \epsilon = 0.1$$



حساب  $\cos^n(\theta)$

$$\cos \theta = \frac{1}{2} (e^{i\theta} + e^{-i\theta})$$

$$\cos^2 \theta = \frac{1}{4} (e^{2i\theta} + e^{-2i\theta} + 2) = \frac{1}{2} \left[ \frac{e^{2i\theta} + e^{-2i\theta}}{2} \right] + \frac{1}{2}$$

$$= \frac{1}{2} (\cos 2\theta + 1)$$

$$\cos^3 \theta = \frac{1}{8} (e^{3i\theta} + 3e^{i\theta} + 3e^{-i\theta} + e^{-3i\theta}) = \frac{1}{4} \cos 3\theta + \frac{3}{4} \cos \theta$$

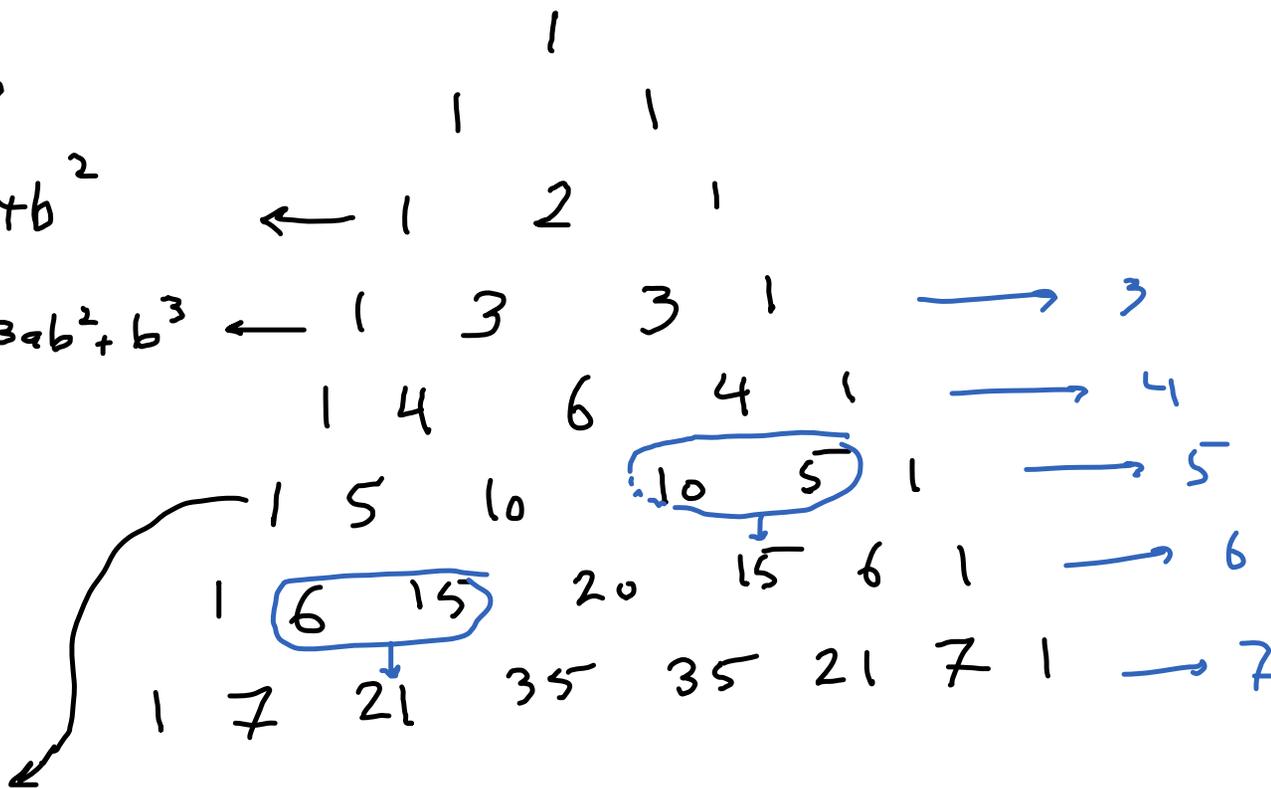
$$(a+b)^3 = a^3 + 3a^2b + 3ab^2 + b^3$$



$$(a+b)^1 = a + b$$

$$(a+b)^2 = a^2 + 2ab + b^2$$

$$(a+b)^3 = a^3 + 3a^2b + 3ab^2 + b^3$$



$$(a+b)^5 = a^5 + 5a^4b + 10a^3b^2 + 10a^2b^3 + 5ab^4 + b^5$$

$$e^{i\theta} \quad e^{-i\theta}$$

$$\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i} \rightarrow (a-b)^n$$



$$(a-b)^2$$

(a -

			1							
			1		1					
		1	-2		1					
		1	-3		3	-1				
		1	<u>4</u>		6	<u>4</u>	1			
		1	-5		10	-10	5	-1		
		1	-6		15	-20	15	-6	1	
		1	-7		21	-35	35	-21	7	-1
							⋮			

$$(a-b)^3 = a^3 - 3a^2b + 3ab^2 - b^3$$



3.1.1

$$\dot{x} = 1 + r x + x^2 = 0 \Rightarrow x^2 + r x + 1 = 0$$

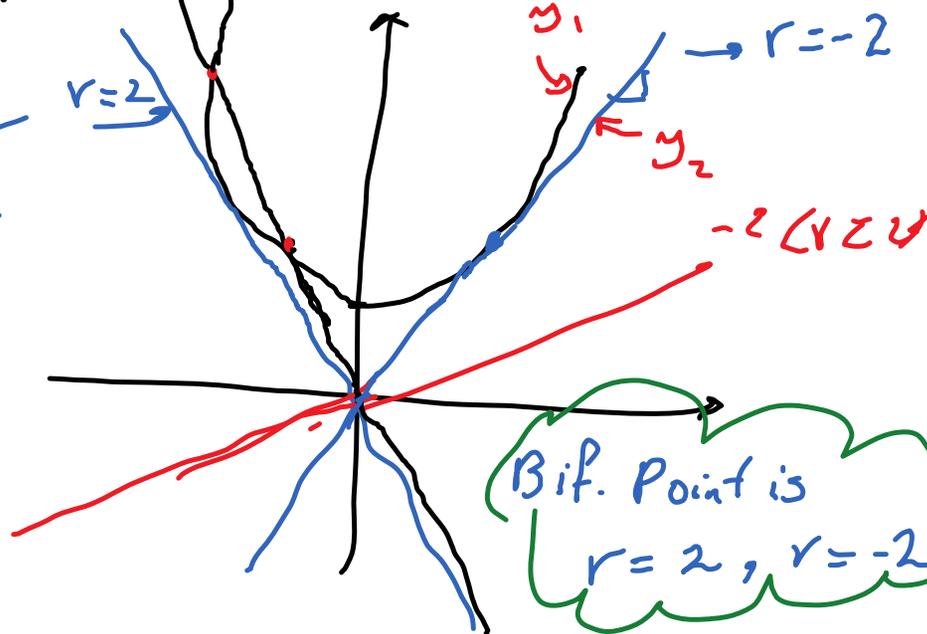
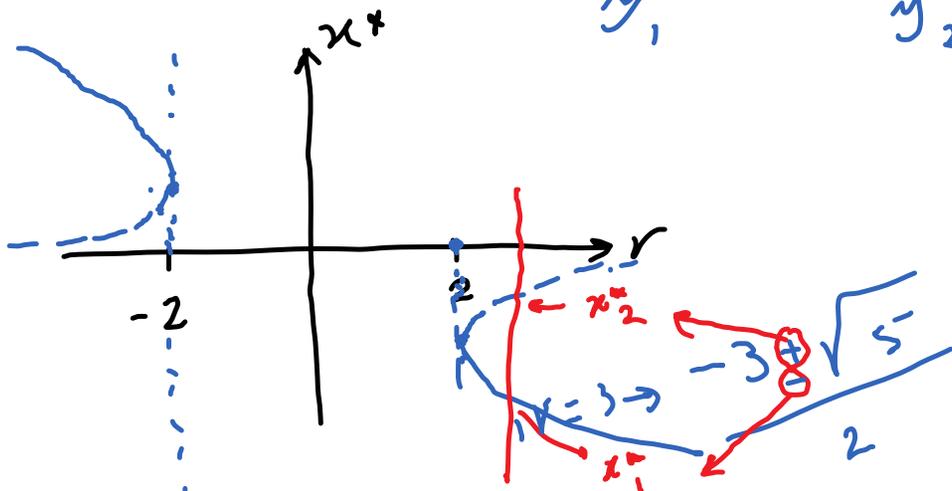
تساوی

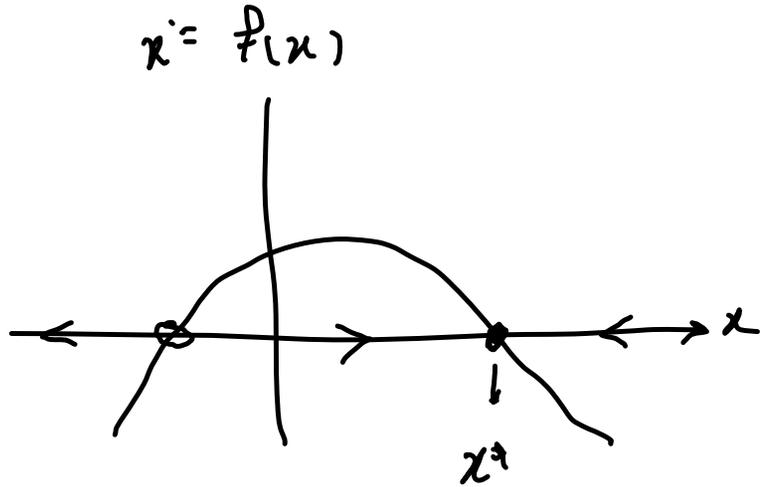
$$x_{1,2} = \frac{-r \pm \sqrt{r^2 - 4}}{2}$$

نقطهٔ تنگی  $-2 < r < 2$

دو نقطهٔ تنگی  $r > 2$ ,  $r < -2$

$$1 + x^2 + r x = 0 \Rightarrow \frac{1 + x^2}{y_1} = \frac{-r x}{y_2}$$





$$f'(x^*) < 0 \rightarrow x^* \text{ پایدار}$$

$$f'(x^*) > 0 \rightarrow x^* \text{ ناپایدار}$$

$$f(x) = x^2 + rx + 1 \rightarrow f'(x) = 2x + r \Rightarrow f'(x^*) = 2x^* + r$$

$$x_{1,2}^* = \frac{-r \pm \sqrt{r^2 - 4}}{2} \Rightarrow f'(x^*) = -r \pm \sqrt{r^2 - 4} + r$$

$$x_1^* \text{ (1)} \rightarrow f'(x_1^*) = +\sqrt{r^2 - 4} > 0 \rightarrow \text{ناپایدار}$$

$$x_2^* \rightarrow f'(x_2^*) = -\sqrt{r^2 - 4} < 0 \rightarrow \text{پایدار}$$